

2.3 Evolution of a particle with external potential. Ehrenfest equation

Given a solution $\psi(x,t)$ of the Schrödinger equation, we write its mean position and mean momentum as follows:

$$\langle x \rangle(t) = \int_{\mathbb{R}^d} x |\psi(x,t)|^2 dx \quad (\langle x \rangle(t) \in \mathbb{R}^d)$$

$$\langle p \rangle(t) = \frac{\hbar}{(2\pi)^d} \int_{\mathbb{R}^d} k |\hat{\psi}(k,t)|^2 dk$$

More generally, if F is a function $\mathbb{R}^d \rightarrow \mathbb{C}$, we write

$$\langle F(x) \rangle(t) = \int_{\mathbb{R}^d} F(x) |\psi(x,t)|^2 dx.$$

Theorem 2.3 (Ehrenfest equations)

Let $\psi(x,t)$ be a classical solution of the Schrödinger equation. We also suppose that $\int |\psi(x,t)|^2 dx = 1$, $\int \|x\| |\psi|^2 < \infty$, $\int \|k\|^2 |\hat{\psi}(k,t)|^2 dk < \infty$, $\int \|\nabla V(x)\| |\psi(x,t)|^2 dx < \infty$. Then

$$(a) \quad \frac{d}{dt} \langle x \rangle(t) = \frac{1}{m} \langle p \rangle(t)$$

$$(b) \quad \frac{d}{dt} \langle p \rangle(t) = - \langle \nabla V(x) \rangle(t)$$

$$(c) \quad \frac{d}{dt} \left(\frac{1}{2m} \langle p^2 \rangle(t) + \langle V(x) \rangle(t) \right) = 0$$

The first two equations are the counterparts of Hamilton's equations for a classical particle, and (c) is the conservation of energy. Notice that a natural guess for (b) could have been $\frac{d}{dt} \langle p \rangle(t) = -\nabla V(\langle x \rangle(t))$, but this turns out to be incorrect.

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Proof: Essentially straightforward calculations. For (a),

$$\begin{aligned} \frac{d}{dt} \langle x_j \rangle(t) &= \stackrel{\text{Thm 2.27 in Folland}}{\int_{\mathbb{R}^d} \frac{\partial}{\partial t} [x_j \overline{\psi(x,t)} \psi(x,t)] dx} \\ &= \int_{\mathbb{R}^d} x_j \left(\frac{\partial \overline{\psi}}{\partial t} \psi + \overline{\psi} \frac{\partial \psi}{\partial t} \right) dx \\ &\stackrel{\text{Schr. eq.}}{=} i \int_{\mathbb{R}^d} x_j \left[\left(-\frac{\hbar}{2m} \Delta \overline{\psi} + \frac{1}{\hbar} V \overline{\psi} \right) \psi - \overline{\psi} \left(-\frac{\hbar}{2m} \Delta \psi + \frac{1}{\hbar} V \psi \right) \right] dx \\ &= i \frac{\hbar}{2m} \int_{\mathbb{R}^d} (-x_j \Delta \overline{\psi} \psi + x_j \overline{\psi} \Delta \psi) dx \\ &\stackrel{\text{by parts}}{=} i \frac{\hbar}{2m} \int_{\mathbb{R}^d} (\nabla(x_j \psi) \cdot \nabla \overline{\psi} - \nabla(x_j \overline{\psi}) \cdot \nabla \psi) dx \\ &= i \frac{\hbar}{2m} \int_{\mathbb{R}^d} \nabla x_j \cdot [\nabla \overline{\psi} \psi - \overline{\psi} \nabla \psi] dx \\ &= i \frac{\hbar}{2m} \int_{\mathbb{R}^d} \left(\frac{\partial \overline{\psi}}{\partial x_j} \psi - \overline{\psi} \frac{\partial \psi}{\partial x_j} \right) dx \\ (*) &\stackrel{\text{by parts}}{=} \frac{i\hbar}{m} \int_{\mathbb{R}^d} \frac{\partial \overline{\psi}}{\partial x_j} \psi dx \\ &\stackrel{\text{Plancherel}}{=} \frac{1}{(2\pi)^d} \frac{i\hbar}{m} \int_{\mathbb{R}^d} \widehat{\frac{\partial \overline{\psi}}{\partial x_j} \psi} dk \\ &= \frac{1}{(2\pi)^d} \frac{\hbar}{m} \int_{\mathbb{R}^d} k_j |\hat{\psi}(k,t)|^2 dk \\ &= \frac{1}{m} \langle p_j \rangle(t). \end{aligned}$$

For (b), we use Eq. (*) above.

$$\begin{aligned} \frac{d}{dt} \langle p_j \rangle(t) &= i\hbar \int_{\mathbb{R}^d} \left[\left(\frac{\partial}{\partial x_j} \frac{\partial}{\partial t} \overline{\psi(x,t)} \right) \psi + \frac{\partial \overline{\psi}}{\partial x_j} \frac{\partial \psi}{\partial t} \right] dx \\ &= i \int_{\mathbb{R}^d} \left[i \left(-\frac{\hbar^2}{2m} \frac{\partial}{\partial x_j} \Delta \overline{\psi} + \frac{\partial}{\partial x_j} V \overline{\psi} \right) \psi - i \frac{\partial \overline{\psi}}{\partial x_j} \left(-\frac{\hbar^2}{2m} \Delta \psi + V \psi \right) \right] dx \\ &\quad = \frac{\partial V}{\partial x_j} \overline{\psi} \psi + V \frac{\partial \overline{\psi}}{\partial x_j} \psi \end{aligned}$$

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$$= \dots = - \int \frac{\partial V}{\partial x_j}(x) |\psi(x)|^2 dx = - \langle (\nabla V)_j(X) \rangle(\psi).$$

Exercise 3: Prove Theorem 2.3 (c). (a) and (b) may help.

□

2.4. Uncertainty principles

The Heisenberg uncertainty principle states that a particle cannot be localised in space, and simultaneously have a definite momentum. It is also a nice inequality of Fourier analysis. We first state the standard result. We also present another result that is valid in $d=1$ only but which has far-reaching consequences. In the next chapter we shall see a different generalisation based on properties of operators.

Theorem 2.4

For any $f \in L^2(\mathbb{R}^d)$ with $\|f\| = 1$, any $x_0, k_0 \in \mathbb{R}^d$, and any $j=1, \dots, d$, we have

$$\int_{\mathbb{R}^d} |x_j - (x_0)_j|^2 |f(x)|^2 dx \cdot \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} |k_j - (k_0)_j|^2 |\hat{f}(k)|^2 dk \geq \frac{1}{4}.$$

If we denote $\langle \Delta X \rangle = (\langle (X - \langle X \rangle)^2 \rangle)^{1/2}$ the mean deviation of X , and similarly for P , the theorem says that $\langle \Delta X \rangle \langle \Delta P \rangle \geq \frac{\hbar}{2}$.

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Proof: We can shift f so that $x_0 = 0$. We can add a phase so that $k_0 = 0$. It is then enough to prove the theorem for $x_0 = k_0 = 0$.

$$\begin{aligned} 1 &= \int |f|^2 \stackrel{\text{by parts}}{=} - \int_{\mathbb{R}^d} x_j \frac{\partial}{\partial x_j} |f(x)|^2 dx \\ &= - \int x_j \frac{\partial \bar{f}}{\partial x_j} f dx - \int x_j \bar{f} \frac{\partial f}{\partial x_j} dx. \end{aligned}$$

Then

$$\begin{aligned} 1 &\leq 2 \int |x_j| |f(x)| \left| \frac{\partial f}{\partial x_j}(x) \right| dx \\ &\stackrel{\text{Cauchy-Schwarz}}{\leq} 2 \left(\int x_j^2 |f(x)|^2 dx \right)^{1/2} \left(\int \left| \frac{\partial f}{\partial x_j} \right|^2 dx \right)^{1/2} \\ &= \frac{1}{(2\pi)^d} \int k_j^2 |\hat{f}|^2 dk \end{aligned}$$

□

Remarks: • The inequality is saturated by gaussian functions, i.e. there is equality iff $f(x) = A e^{i(x-x_0) \cdot k_0} e^{-B(x-x_0)^2}$ with $B > 0$ and $|A|^2 = \left(\frac{B}{\pi}\right)^{d/2}$.

- The theorem somehow assumes that $\int \|x\|^2 |f|^2 < \infty$ and $\int \|k\|^2 |\hat{f}|^2 < \infty$. The left side is understood to be infinite otherwise.
- In the proof we also assumed that $f \in C^1$. But we have proved the inequality for a dense set of functions, and the general claim is obtained by continuity.

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